

Nastavak sa prethodnog časa ...

$$\textcircled{*} \underbrace{\frac{1}{2} \frac{\partial}{\partial t} (\rho_\alpha \langle v^2 \rangle_\alpha)}_{I_{h1}} + \underbrace{\frac{1}{2} \nabla \cdot (\rho_\alpha \langle v^2 \vec{v} \rangle_\alpha)}_{I_{h2}} - \vec{j}_\alpha \cdot \vec{E} = C_{3,\alpha}$$

$$I_{h1} = \frac{\partial}{\partial t} \left( \frac{1}{2} \rho_\alpha \langle v^2 \rangle_\alpha \right) = \frac{\partial}{\partial t} \left( \frac{1}{2} \rho_\alpha \langle (\vec{u}_\alpha + \vec{w}_\alpha) \cdot (\vec{u}_\alpha + \vec{w}_\alpha) \rangle_\alpha \right)$$

$$\vec{v} = \vec{u}_\alpha + \vec{w}_\alpha, \quad p_\alpha = \frac{1}{3} \rho_\alpha \langle w_\alpha^2 \rangle_\alpha, \quad \langle \vec{w}_\alpha \rangle_\alpha = 0$$

$$= \frac{\partial}{\partial t} \left( \frac{1}{2} \rho_\alpha \langle \vec{u}_\alpha \cdot \vec{u}_\alpha + \underbrace{\vec{u}_\alpha \cdot \vec{w}_\alpha}_0 + \underbrace{\vec{w}_\alpha \cdot \vec{u}_\alpha}_0 + \vec{w}_\alpha \cdot \vec{w}_\alpha \rangle_\alpha \right)$$

$$= \frac{\partial}{\partial t} \left( \frac{1}{2} \rho_\alpha \langle u_\alpha^2 + w_\alpha^2 \rangle_\alpha \right) =$$

$$= \frac{\partial}{\partial t} \left( \frac{1}{2} \rho_\alpha u_\alpha^2 \right) + \frac{\partial}{\partial t} \left( \frac{1}{2} \rho_\alpha \langle w_\alpha^2 \rangle_\alpha \right) =$$

$$= \frac{\partial}{\partial t} \left( \frac{1}{2} \rho_\alpha u_\alpha^2 \right) + \frac{\partial}{\partial t} \left( \frac{3}{2} p_\alpha \right) \quad I_{h1}$$

$$I_{h2} = \nabla \cdot \left( \frac{1}{2} \rho_\alpha \langle v^2 \vec{v} \rangle_\alpha \right) \textcircled{=}$$

$$\langle v^2 \vec{v} \rangle_\alpha = \langle (\vec{v} \cdot \vec{v}) \vec{v} \rangle_\alpha =$$

$$\vec{v} = \vec{u}_\alpha + \vec{w}_\alpha$$

$$= \langle [(\vec{u}_\alpha + \vec{w}_\alpha) \cdot (\vec{u}_\alpha + \vec{w}_\alpha)] (\vec{u}_\alpha + \vec{w}_\alpha) \rangle_\alpha =$$

$$= \langle m_\alpha^2 (\vec{u}_\alpha + \vec{w}_\alpha) + 2 \vec{u}_\alpha \cdot \vec{w}_\alpha (\vec{u}_\alpha + \vec{w}_\alpha) + w_\alpha^2 (\vec{u}_\alpha + \vec{w}_\alpha) \rangle_\alpha =$$

$$\langle \vec{u}_\alpha \rangle_\alpha = \vec{u}_\alpha \quad \langle \vec{w}_\alpha \rangle_\alpha = 0$$

$$= m_\alpha^2 \vec{u}_\alpha + m_\alpha^2 \langle \vec{w}_\alpha \rangle_\alpha + 2 \langle (\vec{w}_\alpha \cdot \vec{u}_\alpha) \vec{u}_\alpha \rangle_\alpha + 2 \langle (\vec{u}_\alpha \cdot \vec{w}_\alpha) \vec{w}_\alpha \rangle_\alpha + \langle m_\alpha^2 \vec{u}_\alpha \rangle_\alpha + \langle \vec{w}_\alpha^2 \vec{w}_\alpha \rangle_\alpha =$$

$$= m_\alpha^2 \vec{u}_\alpha + 2 \vec{u}_\alpha \cdot \langle \vec{w}_\alpha \otimes \vec{w}_\alpha \rangle_\alpha + \langle m_\alpha^2 \rangle_\alpha \vec{u}_\alpha + \langle \vec{w}_\alpha^2 \vec{w}_\alpha \rangle_\alpha$$

$$\Rightarrow \nabla \cdot \left( \frac{1}{2} S_\alpha (m_\alpha^2 \vec{u}_\alpha + 2 \vec{u}_\alpha \cdot \langle \vec{w}_\alpha \otimes \vec{w}_\alpha \rangle_\alpha + \langle m_\alpha^2 \rangle_\alpha \vec{u}_\alpha + \langle m_\alpha^2 \vec{w}_\alpha \rangle_\alpha) \right) \Rightarrow^*$$

$$1) \hat{g}_\alpha = \frac{1}{2} S_\alpha \langle m_\alpha^2 \vec{w}_\alpha \rangle_\alpha$$

$$2) \hat{p}_\alpha = S_\alpha \langle \vec{w}_\alpha \otimes \vec{w}_\alpha \rangle_\alpha$$

$$\left\{ \begin{array}{l} 3) \quad 3p_\alpha = \rho_\alpha \langle u_\alpha^2 \rangle_\alpha \end{array} \right.$$

$$\begin{aligned} \Rightarrow \nabla \cdot \left( \frac{1}{2} \rho_\alpha u_\alpha^2 \vec{u}_\alpha + \hat{p}_\alpha \cdot \vec{u}_\alpha + \frac{3}{2} p_\alpha \vec{u}_\alpha + \vec{g}_\alpha \right) \\ = \nabla \cdot \left( \frac{1}{2} \rho_\alpha u_\alpha^2 \vec{u}_\alpha \right) + \nabla \cdot \vec{g}_\alpha + \frac{3}{2} p_\alpha \nabla \cdot \vec{u}_\alpha + \frac{3}{2} \nabla p_\alpha \cdot \vec{u}_\alpha + \end{aligned}$$

$\nabla \cdot (T\vec{A})$

$$+ \nabla \cdot (\hat{p}_\alpha \cdot \vec{u}_\alpha) \quad I_{42}$$

$$\Rightarrow I_{41} + I_{42}$$

$$\frac{\partial}{\partial t} \left( \frac{1}{2} \rho_\alpha u_\alpha^2 \right) + \frac{\partial}{\partial t} \left( \frac{3}{2} p_\alpha \right) + \nabla \cdot \left( \frac{1}{2} \rho_\alpha u_\alpha^2 \vec{u}_\alpha \right) + \nabla \cdot \vec{g}_\alpha +$$

$$+ \frac{3}{2} p_\alpha \nabla \cdot \vec{u}_\alpha + \frac{3}{2} \nabla p_\alpha \cdot \vec{u}_\alpha + \nabla \cdot (\hat{p}_\alpha \cdot \vec{u}_\alpha) =$$

$$= \vec{f}_\alpha \cdot \vec{E} + C_{3,\alpha}$$

$$I_{51} = \frac{\partial}{\partial t} \left( \frac{1}{2} \rho_\alpha u_\alpha^2 \right) + \nabla \cdot \left( \frac{1}{2} \rho_\alpha u_\alpha^2 \vec{u}_\alpha \right) =$$

$$= \frac{1}{2} u_\alpha^2 \frac{\partial \rho_\alpha}{\partial t} + \frac{1}{2} \rho_\alpha \frac{\partial}{\partial t} (\vec{u}_\alpha \cdot \vec{u}_\alpha) +$$

$$+ \rho_\alpha \vec{u}_\alpha \cdot \nabla \left( \frac{1}{2} u_\alpha^2 \right) + \frac{1}{2} u_\alpha^2 \nabla \cdot (\rho_\alpha \vec{u}_\alpha) =$$

$$= \frac{1}{2} u_\alpha^2 \left( \frac{\partial \rho_\alpha}{\partial t} + \nabla \cdot (\rho_\alpha \vec{u}_\alpha) \right) + \cancel{2} \frac{\cancel{1}}{\cancel{2}} \rho_\alpha \vec{u}_\alpha \cdot \frac{\partial \vec{u}_\alpha}{\partial t} +$$

$$+ \rho_\alpha \vec{u}_\alpha \cdot \nabla \left( \frac{1}{2} \vec{u}_\alpha \cdot \vec{u}_\alpha \right) \stackrel{*}{=} \stackrel{*}{*}$$

$$\nabla (\vec{A} \cdot \vec{B}) = \vec{A} \times (\nabla \times \vec{B}) + \vec{B} \times (\nabla \times \vec{A}) +$$

$$+ (\vec{A} \cdot \nabla) \vec{B} + (\vec{B} \cdot \nabla) \vec{A}$$

$$\Rightarrow \nabla \left( \frac{1}{2} \vec{u}_\alpha \cdot \vec{u}_\alpha \right) = \cancel{\frac{1}{2}} \left( \cancel{2} \vec{u}_\alpha \times (\nabla \times \vec{u}_\alpha) + \right.$$

$$\left. + \cancel{2} (\vec{u}_\alpha \cdot \nabla) \vec{u}_\alpha \right)$$

$$\nabla \left( \frac{1}{2} u_\alpha^2 \right) = \vec{u}_\alpha \times (\nabla \times \vec{u}_\alpha) + (\vec{u}_\alpha \cdot \nabla) \vec{u}_\alpha$$

$$\vec{u}_\alpha \cdot \nabla \left( \frac{1}{2} u_\alpha^2 \right) = \underbrace{\vec{u}_\alpha \cdot (\vec{u}_\alpha \times (\nabla \times \vec{u}_\alpha))}_0 + \vec{u}_\alpha \cdot (\vec{u}_\alpha \cdot \nabla) \vec{u}_\alpha$$

$$\stackrel{*}{=} \stackrel{*}{*} \frac{1}{2} u_\alpha^2 \left( \frac{\partial \rho_\alpha}{\partial t} + \nabla \cdot (\rho_\alpha \vec{u}_\alpha) \right) + \rho_\alpha \vec{u}_\alpha \cdot \frac{\partial \vec{u}_\alpha}{\partial t} +$$

$$+ \rho_\alpha \vec{u}_\alpha \cdot (\vec{u}_\alpha \cdot \nabla) \vec{u}_\alpha =$$

$$= \frac{1}{2} n_\alpha^2 \left( \frac{\partial p_\alpha}{\partial t} + \nabla \cdot (p_\alpha \vec{u}_\alpha) \right) +$$

jedna kont.

$$+ p_\alpha n_\alpha \cdot \left( \frac{\partial \vec{u}_\alpha}{\partial t} + (\vec{u}_\alpha \cdot \nabla) \vec{u}_\alpha \right)$$

jedna jedna

$$\circledast \frac{3}{2} \left( \frac{\partial}{\partial t} + \vec{u}_\alpha \cdot \nabla \right) p_\alpha + \frac{1}{2} n_\alpha^2 \left( \frac{\partial p_\alpha}{\partial t} + \nabla \cdot (p_\alpha \vec{u}_\alpha) \right) +$$

d/dt

$$+ p_\alpha \vec{u}_\alpha \cdot \left( \frac{\partial \vec{u}_\alpha}{\partial t} + (\vec{u}_\alpha \cdot \nabla) \vec{u}_\alpha \right) + \frac{3}{2} p_\alpha \nabla \cdot \vec{u}_\alpha +$$

C<sub>1,2</sub>

$$+ \nabla \cdot \vec{g}_\alpha + \nabla \cdot (\hat{p}_\alpha \cdot \vec{u}_\alpha) = \vec{f}_\alpha \cdot \vec{E} + C_{3,\alpha}$$

$$p_\alpha \frac{\partial \vec{u}_\alpha}{\partial t} + p_\alpha \vec{u}_\alpha \cdot (\nabla \otimes \vec{u}_\alpha) = p_\alpha \frac{d\vec{u}_\alpha}{dt}$$

$$\left[ p_\alpha \frac{d\vec{u}_\alpha}{dt} = -\nabla \cdot \hat{p}_\alpha + p_\alpha^{el} \vec{E} + \vec{f}_\alpha \times \vec{B} + \vec{C}_{2,\alpha} - \vec{u}_\alpha C_{1,\alpha} \right]$$

$$\Rightarrow \frac{3}{2} \frac{dp_\alpha}{dt} + \frac{1}{2} n_\alpha^2 C_{1,\alpha} + \vec{u}_\alpha \cdot \left[ p_\alpha \frac{d\vec{u}_\alpha}{dt} \right] +$$

$$+ \frac{3}{2} p_\alpha \nabla \cdot \vec{u}_\alpha + \nabla \cdot \vec{g}_\alpha + \nabla \cdot (\hat{P}_\alpha \cdot \vec{u}_\alpha) = \vec{j}_\alpha \cdot \vec{E} + C_{3,\alpha}$$

$$\nabla \cdot (\hat{T} \cdot \vec{A}) = \vec{A} \cdot (\nabla \cdot \hat{T}) + (\hat{T} \cdot \nabla) \cdot \vec{A}$$

$$\begin{aligned} \frac{3}{2} \frac{dp_\alpha}{dt} + \frac{1}{2} \mu_\alpha^2 C_{1,\alpha} + \vec{u}_\alpha \cdot \left( -\nabla \cdot \hat{P}_\alpha + \cancel{\vec{S}_\alpha} \cdot \vec{E} + \vec{j}_\alpha \times \vec{B} + \right. \\ \left. + \vec{C}_{2,\alpha} - \vec{u}_\alpha C_{1,\alpha} \right) + \frac{3}{2} p_\alpha \nabla \cdot \vec{u}_\alpha + \nabla \cdot \vec{g}_\alpha + \vec{u}_\alpha \cdot (\nabla \cdot \hat{P}_\alpha) + \\ + (\hat{P}_\alpha \cdot \nabla) \cdot \vec{u}_\alpha = \vec{j}_\alpha \cdot \vec{E} + C_{3,\alpha} \end{aligned}$$

$$\begin{aligned} \frac{3}{2} \frac{dp_\alpha}{dt} - \frac{1}{2} \mu_\alpha^2 C_{1,\alpha} + \vec{u}_\alpha \cdot \vec{C}_{2,\alpha} + \frac{3}{2} p_\alpha \nabla \cdot \vec{u}_\alpha + \\ + \nabla \cdot \vec{g}_\alpha + (\hat{P}_\alpha \cdot \nabla) \cdot \vec{u}_\alpha = C_{3,\alpha} \end{aligned}$$

$$\begin{aligned} \left[ \frac{3}{2} \frac{dp_\alpha}{dt} + \frac{3}{2} p_\alpha \nabla \cdot \vec{u}_\alpha + \nabla \cdot \vec{g}_\alpha + (\hat{P}_\alpha \cdot \nabla) \cdot \vec{u}_\alpha = \right. \\ \left. = \frac{1}{2} \mu_\alpha^2 C_{1,\alpha} - \vec{u}_\alpha \cdot \vec{C}_{2,\alpha} + C_{3,\alpha} \right] \end{aligned}$$

• Zusammenhang elastische Indizes:

$$C_{1,\alpha} = 0, \quad \forall \alpha$$

$$e = \frac{1}{\rho g^{-1}} \frac{p}{\rho} \quad \gamma_f = \frac{c_p}{c_v}$$

$$\rho_\alpha e_\alpha = \frac{3}{2} p_\alpha, \quad \gamma_g = \frac{5}{3} \quad | \text{3. step. slab.}$$

$$\Rightarrow \frac{3}{2} \frac{\partial p_\alpha}{\partial t} + \frac{3}{2} \vec{u}_\alpha \cdot \nabla p_\alpha + \nabla \cdot \left( \frac{1}{2} \rho_\alpha u_\alpha^2 \vec{u}_\alpha \right) +$$

$$+ \frac{\partial}{\partial t} \left( \frac{1}{2} \rho_\alpha u_\alpha^2 \right) + \nabla \cdot \vec{g}_\alpha + \frac{3}{2} p_\alpha \nabla \cdot \vec{u}_\alpha +$$

$$+ \nabla \cdot (\hat{p}_\alpha \cdot \vec{u}_\alpha) = \vec{f}_\alpha \cdot \vec{E} + C_{3,\alpha}$$

$$\Rightarrow \frac{\partial}{\partial t} (\rho_\alpha e_\alpha) + \vec{u}_\alpha \cdot \nabla (\rho_\alpha e_\alpha) + \rho_\alpha e_\alpha \nabla \cdot \vec{u}_\alpha +$$

$$+ \nabla \cdot \left( \frac{1}{2} \rho_\alpha u_\alpha^2 \vec{u}_\alpha \right) + \frac{\partial}{\partial t} \left( \frac{1}{2} \rho_\alpha u_\alpha^2 \right) + \nabla \cdot \vec{g}_\alpha$$

$$+ \nabla \cdot (\hat{p}_\alpha \cdot \vec{u}_\alpha) = \vec{f}_\alpha \cdot \vec{E} + C_{3,\alpha}$$

$$\nabla \cdot (\rho_\alpha e_\alpha \vec{u}_\alpha)$$

$$\frac{\partial}{\partial t} \left( \frac{1}{2} \rho_\alpha u_\alpha^2 + \rho_\alpha \epsilon_\alpha \right) + \nabla \cdot \left[ \left( \frac{1}{2} \rho_\alpha u_\alpha^2 + \rho_\alpha \epsilon_\alpha \right) \vec{u}_\alpha + \vec{q}_\alpha + \hat{p}_\alpha \cdot \vec{u}_\alpha \right] = \vec{j}_\alpha \cdot \vec{E} + C_{3,\alpha}$$

$$\vec{q} = \frac{1}{2} \sum_\alpha \rho_\alpha \langle (\vec{v} - \vec{u})^2 (\vec{v} - \vec{u}) \rangle_\alpha$$

$$\vec{q}_\alpha = \frac{1}{2} \rho_\alpha \langle w_\alpha^2 \vec{w}_\alpha \rangle_\alpha$$

$$\vec{q} = \sum_\alpha \frac{1}{2} \rho_\alpha u_{diff,\alpha}^2 \vec{u}_{diff,\alpha} + \sum_\alpha \vec{q}_\alpha + \sum_\alpha \frac{3}{2} p_\alpha \vec{u}_{diff,\alpha} + \sum_\alpha \hat{p}_\alpha \cdot \vec{u}_{diff,\alpha}$$

$$\rho_\alpha \langle v^2 \rangle_\alpha = \rho_\alpha u_\alpha^2 + 3p_\alpha$$

$$\sum_\alpha \frac{1}{2} \rho_\alpha \langle v^2 \rangle_\alpha = \sum_\alpha \frac{1}{2} \rho_\alpha u_\alpha^2 + \frac{3}{2} \sum_\alpha p_\alpha$$

• supaya skal. partisiak:

$$p = \sum_\alpha p_\alpha + \frac{1}{3} \sum_\alpha \rho_\alpha u_{diff,\alpha}^2$$

$$\sum_\alpha p_\alpha = p - \frac{1}{3} \sum_\alpha \rho_\alpha u_{diff,\alpha}^2$$



$$\rightarrow \sum_{\alpha} \frac{1}{2} \rho_{\alpha} \langle v^2 \rangle_{\alpha} = \sum_{\alpha} \frac{1}{2} \rho_{\alpha} u_{\alpha}^2 + \frac{3}{2} \sum_{\alpha} \rho_{\alpha}$$

$$= \sum_{\alpha} \frac{1}{2} \rho_{\alpha} u_{\alpha}^2 + \frac{3}{2} \rho - \frac{1}{2} \sum_{\alpha} \rho_{\alpha} u_{diff, \alpha}^2 =$$

$$\vec{u}_{diff, \alpha} = \vec{u}_{\alpha} - \vec{u}$$

$$= \sum_{\alpha} \frac{1}{2} \rho_{\alpha} u_{\alpha}^2 + \frac{3}{2} \rho - \frac{1}{2} \sum_{\alpha} \rho_{\alpha} (\vec{u}_{\alpha} - \vec{u}) \cdot (\vec{u}_{\alpha} - \vec{u}) =$$

$$= \cancel{\sum_{\alpha} \frac{1}{2} \rho_{\alpha} u_{\alpha}^2} + \frac{3}{2} \rho - \cancel{\frac{1}{2} \sum_{\alpha} \rho_{\alpha} u_{\alpha}^2} - \frac{1}{2} \sum_{\alpha} \rho_{\alpha} u^2 +$$

$$+ 2 \cdot \frac{1}{2} \sum_{\alpha} \rho_{\alpha} \vec{u}_{\alpha} \cdot \vec{u} =$$

$$= \frac{3}{2} \rho - \frac{1}{2} \rho u^2 + \rho u^2$$

$$= \frac{3}{2} \rho + \frac{1}{2} \rho u^2$$

$$\rho + \frac{1}{3} \rho u^2 = \sum_{\alpha} \rho_{\alpha} + \frac{1}{3} \sum_{\alpha} \rho_{\alpha} u_{diff, \alpha}^2 + \frac{1}{3} \rho u^2$$

$$= \sum_{\alpha} \rho_{\alpha} + \frac{1}{3} \rho u^2 + \frac{1}{3} \sum_{\alpha} \rho_{\alpha} (\vec{u}_{\alpha} - \vec{u}) \cdot (\vec{u}_{\alpha} - \vec{u}) =$$

$$= \sum_{\alpha} p_{\alpha} + \frac{1}{3} \rho u^2 + \frac{1}{3} \sum_{\alpha} p_{\alpha} u_{\alpha}^2 + \frac{1}{3} \left( \sum_{\alpha} p_{\alpha} \right) u^2 -$$

$$- \frac{2}{3} \left( \sum_{\alpha} p_{\alpha} \vec{u}_{\alpha} \right) \cdot \vec{u} =$$

$$= \sum_{\alpha} p_{\alpha} + \cancel{\frac{1}{3} \rho u^2} + \frac{1}{3} \sum_{\alpha} p_{\alpha} u_{\alpha}^2 + \cancel{\frac{1}{3} \rho u^2} -$$

$$\cancel{\frac{2}{3} \rho u^2} =$$

$$p + \frac{1}{3} \rho u^2 = \sum_{\alpha} p_{\alpha} + \frac{1}{3} \sum_{\alpha} p_{\alpha} u_{\alpha}^2$$

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$$\frac{\partial}{\partial t} \left( \frac{1}{2} \rho_{\alpha} \langle v^2 \rangle_{\alpha} \right) + \nabla \cdot \left( \frac{1}{2} \rho_{\alpha} \langle v^2 \vec{v} \rangle_{\alpha} \right) = \vec{f}_{\alpha} \cdot \vec{E} + C_{31\alpha}$$

$$\cancel{\sum_{\alpha}} \quad , \quad \sum_{\alpha} C_{31\alpha} = 0$$

$$\frac{\partial}{\partial t} \left( \frac{1}{2} \sum_{\alpha} \rho_{\alpha} \langle v^2 \rangle_{\alpha} \right) + \nabla \cdot \left( \frac{1}{2} \sum_{\alpha} \rho_{\alpha} \langle v^2 \vec{v} \rangle_{\alpha} \right) =$$

$$= \sum_{\alpha} \vec{f}_{\alpha} \cdot \vec{E} \quad \text{⊗}$$

$$\frac{1}{2} \rho_\alpha \langle v^2 \vec{v} \rangle_\alpha = \frac{1}{2} \rho_\alpha \left( u_\alpha^2 \vec{u}_\alpha + \langle \vec{w}_\alpha^2 \vec{w}_\alpha \rangle_\alpha + \langle w_\alpha^2 \rangle_\alpha \vec{u}_\alpha + \right.$$

$$\left. \vec{u}_\alpha = \vec{u}_{diff,\alpha} + \vec{u} \right)$$

$$\rho_\alpha = \frac{1}{3} \rho_\alpha \langle w_\alpha^2 \rangle_\alpha$$

$$+ 2 \langle \vec{w}_\alpha \otimes \vec{w}_\alpha \rangle_\alpha \cdot \vec{u}_\alpha =$$

$$= \frac{1}{2} \rho_\alpha \left( (u_{diff,\alpha}^2 + 2\vec{u} \cdot \vec{u}_{diff,\alpha} + u^2) (\vec{u}_{diff,\alpha} + \vec{u}) \right) +$$

$$+ \frac{1}{2} \rho_\alpha \langle w_\alpha^2 \vec{w}_\alpha \rangle_\alpha + \frac{1}{2} \rho_\alpha \langle w_\alpha^2 \rangle_\alpha \vec{u}_\alpha +$$

$$+ \frac{1}{2} \cdot 2 \rho_\alpha \langle \vec{w}_\alpha \otimes \vec{w}_\alpha \rangle_\alpha \cdot \vec{u}_\alpha =$$

$$= \frac{1}{2} \rho_\alpha (u_{diff,\alpha}^2 + 2\vec{u} \cdot \vec{u}_{diff,\alpha} + u^2) (\vec{u}_{diff,\alpha} + \vec{u}) +$$

$$+ \vec{g}_\alpha + \frac{3}{2} \rho_\alpha + \hat{\rho}_\alpha \cdot \vec{u}_\alpha$$

— — — — —

$$\sum_\alpha \frac{1}{2} \rho_\alpha \langle v^2 \vec{v} \rangle_\alpha =$$

$$= \sum_\alpha \frac{1}{2} \rho_\alpha u_{diff,\alpha}^2 \vec{u}_{diff,\alpha} + \sum_\alpha \frac{1}{2} \rho_\alpha u_{diff,\alpha}^2 \vec{u} +$$

$$\begin{aligned}
& + \sum_{\alpha} \frac{1}{2} \rho_{\alpha} \cdot 2(\vec{u} \cdot \vec{u}_{diff\alpha}) \vec{u}_{diff\alpha} + \sum_{\alpha} \frac{1}{2} \rho_{\alpha} \cdot 2(\vec{u} \cdot \vec{u}_{diff\alpha}) \vec{u} + \\
& \leftarrow \sum_{\alpha} \frac{1}{2} \rho_{\alpha} u^2 \vec{u}_{diff\alpha} + \sum_{\alpha} \frac{1}{2} \rho_{\alpha} u^2 \vec{u} + \sum_{\alpha} \vec{g}_{\alpha} + \sum_{\alpha} \frac{3}{2} \rho_{\alpha} \vec{u} \\
& + \sum_{\alpha} \hat{p}_{\alpha} \cdot \vec{u}_{diff\alpha} + \sum_{\alpha} \hat{p}_{\alpha} \cdot \vec{u}
\end{aligned}$$

$$\sum_{\alpha} \rho_{\alpha} \vec{u}_{diff} = 0$$

$$\begin{aligned}
\sum_{\alpha} \frac{1}{2} \rho_{\alpha} \langle v^2 \vec{v} \rangle_{\alpha} &= \sum_{\alpha} \frac{1}{2} \rho_{\alpha} u_{diff\alpha}^2 \vec{u}_{diff\alpha} + \sum_{\alpha} \frac{1}{2} \rho_{\alpha} u_{diff\alpha}^2 \vec{u} \\
& + \sum_{\alpha} \frac{1}{2} \rho_{\alpha} u^2 \vec{u} + \sum_{\alpha} \rho_{\alpha} (\vec{u} \cdot \vec{u}_{diff\alpha}) \vec{u}_{diff\alpha} + \\
& + \sum_{\alpha} \vec{g}_{\alpha} + \sum_{\alpha} \frac{3}{2} \rho_{\alpha} \vec{u}_{diff\alpha} + \sum_{\alpha} \frac{3}{2} \rho_{\alpha} \vec{u} + \\
& + \sum_{\alpha} \hat{p}_{\alpha} \cdot \vec{u}_{diff\alpha} + \sum_{\alpha} \hat{p}_{\alpha} \cdot \vec{u}
\end{aligned}$$

$\vec{u} \cdot \hat{p} = \hat{p} \cdot \vec{u}$   
 $\hat{p}$  - symetrická!

$$\begin{aligned}
\sum_{\alpha} \frac{1}{2} \rho_{\alpha} \langle v^2 \vec{v} \rangle_{\alpha} &= \vec{g} + \vec{u} \cdot \hat{p} + \\
& + \sum_{\alpha} \frac{1}{2} \rho_{\alpha} (u_{diff\alpha}^2 + u^2) \vec{u} + \sum_{\alpha} \frac{3}{2} \rho_{\alpha} \vec{u}
\end{aligned}$$

masukkan  $\otimes$ :

$$\frac{\partial}{\partial t} \left( \frac{3}{2} p + \frac{1}{2} \rho u^2 \right) + \nabla \cdot \left( \vec{q} + \vec{u} \cdot \hat{p} + \sum_{\alpha} \frac{1}{2} \rho_{\alpha} (u_{diff\alpha}^2 + u^2) \vec{u} + \sum_{\alpha} \frac{3}{2} p_{\alpha} \vec{u} \right) = \vec{f} \cdot \vec{E}$$

$$\left. \begin{aligned} \frac{1}{2} \sum_{\alpha} \rho_{\alpha} u^2 diff_{\alpha} \vec{u} &= \frac{3}{2} p \vec{u} - \frac{3}{2} \sum_{\alpha} p_{\alpha} \vec{u} \\ \text{Iz} \quad p &= \sum_{\alpha} p_{\alpha} + \frac{1}{3} \sum_{\alpha} \rho_{\alpha} u^2 diff_{\alpha} \end{aligned} \right\}$$

$$\frac{\partial}{\partial t} \left( \frac{3p}{2} + \frac{1}{2} \rho u^2 \right) + \nabla \cdot \left( \vec{q} + \vec{u} \cdot \hat{p} + \frac{3}{2} p \vec{u} - \cancel{\frac{3}{2} \sum_{\alpha} p_{\alpha} \vec{u}} + \sum_{\alpha} \frac{1}{2} \rho_{\alpha} u^2 \vec{u} + \sum_{\alpha} \cancel{\frac{3}{2} p_{\alpha} \vec{u}} \right) = \vec{f} \cdot \vec{E}$$

$$\left[ \frac{\partial}{\partial t} \left( \frac{3p}{2} + \frac{1}{2} \rho u^2 \right) + \nabla \cdot \left( \left( \frac{3}{2} p + \frac{1}{2} \rho u^2 \right) \vec{u} + \vec{q} + \vec{u} \cdot \hat{p} \right) \right] = \vec{f} \cdot \vec{E} \quad \text{jdna}$$

$$\frac{3p}{2} = \rho e$$

$$\left[ \frac{\partial}{\partial t} \left( \rho e + \frac{1}{2} \rho u^2 \right) + \nabla_{\bullet} \left( \left( \rho e + \frac{1}{2} \rho u^2 \right) \vec{u} + \vec{u} \cdot \vec{p} + \vec{q} \right) = \vec{j} \cdot \vec{E} \right]$$

