

VEKTORSKA ALGEBRA I ANALIZA

- skalar = brojevi
- vektor $\vec{a} = (a_1 \ a_2 \ a_3)$
- tenzori

⊗ reprezentacije

• skalar $[]_{1 \times 1}$

• vektore $[]_{1 \times 3}$ ili $[]_{3 \times 1}$

• tenzori $[]_{3 \times 3}$

$$\hat{T} = \begin{bmatrix} T_{11} & T_{12} & T_{13} \\ T_{21} & T_{22} & T_{23} \\ T_{31} & T_{32} & T_{33} \end{bmatrix}$$

$[]_{3 \times 1}$

3D Dekartovom
sistemom

• def

1) skalarni proizvod \vec{a}, \vec{b}

$$\vec{a} \cdot \vec{b} = \begin{matrix} 1 \times 3 \\ \left[a_1 \ a_2 \ a_3 \right] \end{matrix} \begin{matrix} 3 \times 1 \\ \left[\begin{matrix} b_1 \\ b_2 \\ b_3 \end{matrix} \right] \end{matrix} = \begin{matrix} 1 \times 1 \\ a_1 b_1 + a_2 b_2 + a_3 b_3 \end{matrix}$$

2) vektorskim proizvodom \vec{a}, \vec{b}

$$\vec{a} \times \vec{b} = \begin{vmatrix} \vec{e}_x & \vec{e}_y & \vec{e}_z \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix} = \begin{bmatrix} a_2 b_3 - a_3 b_2 \\ a_3 b_1 - a_1 b_3 \\ a_1 b_2 - a_2 b_1 \end{bmatrix} \begin{matrix} \swarrow \vec{e}_x \\ \swarrow \vec{e}_y \\ \swarrow \vec{e}_z \end{matrix}$$

3) tenzorski (dijadski) proizvod \vec{a}, \vec{b}

$$\vec{a} \otimes \vec{b} = \vec{a} \otimes \vec{b}$$

(komponente $a_i b_j$)

klasificirano "matrice"

$$\vec{a} \otimes \vec{b} = \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} \begin{bmatrix} b_1 & b_2 & b_3 \end{bmatrix} =$$

$\underset{=}{3 \times 1} \quad \longleftarrow \quad \longrightarrow \quad \underset{=}{1 \times 3}$

$$\begin{bmatrix} a_1 b_1 & a_1 b_2 & a_1 b_3 \\ a_2 b_1 & a_2 b_2 & a_2 b_3 \\ a_3 b_1 & a_3 b_2 & a_3 b_3 \end{bmatrix}_{3 \times 3}$$

$$\otimes \quad \overset{a}{T} \cdot \vec{v} = \begin{bmatrix} T_{11} & T_{12} & T_{13} \\ T_{21} & T_{22} & T_{23} \\ T_{31} & T_{32} & T_{33} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} T_{11} v_1 + T_{12} v_2 + T_{13} v_3 \\ T_{21} v_1 + T_{22} v_2 + T_{23} v_3 \\ T_{31} v_1 + T_{32} v_2 + T_{33} v_3 \end{bmatrix}$$

$3 \times 3 \quad \longleftarrow \quad \longrightarrow \quad 3 \times 1$

$$\textcircled{*} \vec{v} \cdot \vec{T} = \begin{bmatrix} N_1 & N_2 & N_3 \end{bmatrix} \begin{bmatrix} T_{11} & T_{21} & T_{31} \\ T_{12} & T_{22} & T_{32} \\ T_{13} & T_{23} & T_{33} \end{bmatrix} = \begin{matrix} (1 \times 3) \\ N_1 T_{11} + N_2 T_{12} + N_3 T_{13} \\ N_1 T_{21} + N_2 T_{22} + N_3 T_{23} \\ N_1 T_{31} + N_2 T_{32} + N_3 T_{33} \end{matrix}$$

$$\textcircled{*} \vec{T} = \begin{bmatrix} T_{11} & T_{21} & T_{31} \\ T_{12} & T_{22} & T_{32} \\ T_{13} & T_{23} & T_{33} \end{bmatrix} = \begin{bmatrix} \vec{T}_1 & \vec{T}_2 & \vec{T}_3 \end{bmatrix}$$

$\underbrace{\quad}_{\vec{T}_1} \quad \underbrace{\quad}_{\vec{T}_2} \quad \underbrace{\quad}_{\vec{T}_3}$

$$\textcircled{*} \text{operator nabla } \nabla : \quad \nabla = \begin{bmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{bmatrix} = \begin{bmatrix} \partial_x \\ \partial_y \\ \partial_z \end{bmatrix}$$

do ma'ci: pokazati (pomoću matrica): Ako je \hat{T} simetričan,
tada važi $\vec{v} \cdot \hat{T} = \hat{T} \cdot \vec{v}$.

$$\hat{T} = \begin{bmatrix} T_1 & T_4 & T_5 \\ T_4 & T_2 & T_6 \\ T_5 & T_6 & T_3 \end{bmatrix} \quad \begin{matrix} \text{!} & [&] \\ \text{?} & & [&] \end{matrix}$$

(*) def: 1) Skalarno polje: $T(\vec{r}, t)$

$$dT = d\vec{r} \cdot (\nabla T)$$

$$\frac{dT}{dt} = \frac{\partial T}{\partial t} + \vec{v} \cdot (\nabla T)$$

2) vektorislu poigö: $\vec{A}(\vec{r}, t)$

$$d\vec{A} = d\vec{r} \cdot (\nabla \otimes \vec{A})$$

$$\frac{d\vec{A}}{dt} = \frac{\partial \vec{A}}{\partial t} + \vec{v} \cdot (\nabla \otimes \vec{A})$$

lokali tensor
vekt. poija

- distansija

$$\vec{v} \cdot (\nabla T) = \underset{1 \times 3}{[\quad]} \cdot \left(\underset{3 \times 1}{[\quad]} \underset{1 \times 1}{[\quad]} \right) = \underset{1 \times 3}{[\quad]} \underset{3 \times 1}{[\quad]} = \underset{1 \times 1}{[\quad]}$$

$$\vec{v} \cdot (\nabla \otimes \vec{A}) = \underset{1 \times 3}{[\quad]} \cdot \left(\underset{3 \times 3}{[\quad]} \underset{3 \times 1}{[\quad]} \right) = \underset{1 \times 3}{[\quad]} \underset{3 \times 1}{[\quad]} = \underset{1 \times 1}{[\quad]}$$

$$\textcircled{1} \quad \nabla \cdot (\vec{A} \otimes \vec{B}) = ?$$

$$\vec{A} \otimes \vec{B} = \begin{bmatrix} A_x \\ A_y \\ A_z \end{bmatrix} \begin{bmatrix} B_x & B_y & B_z \end{bmatrix} = \begin{bmatrix} A_x B_x & A_x B_y & A_x B_z \\ A_y B_x & A_y B_y & A_y B_z \\ A_z B_x & A_z B_y & A_z B_z \end{bmatrix}$$

$$\nabla \cdot (\vec{A} \otimes \vec{B}) = \begin{bmatrix} \partial_x & \partial_y & \partial_z \end{bmatrix} \begin{bmatrix} A_x B_x & A_x B_y & A_x B_z \\ A_y B_x & A_y B_y & A_y B_z \\ A_z B_x & A_z B_y & A_z B_z \end{bmatrix} =$$

$$= \begin{bmatrix} \partial_x (A_x B_x) + \partial_y (A_y B_x) + \partial_z (A_z B_x); \\ \partial_x (A_x B_y) + \partial_y (A_y B_y) + \partial_z (A_z B_y); \\ \partial_x (A_x B_z) + \partial_y (A_y B_z) + \partial_z (A_z B_z) \end{bmatrix}$$

$$\begin{aligned}
 \partial_x (A_x B_x) + \partial_y (A_y B_x) + \partial_z (A_z B_x) &= B_x (\partial_x A_x + \partial_y A_y + \partial_z A_z) + \\
 &+ A_x \partial_x B_x + A_y \partial_y B_x + A_z \partial_z B_x = \\
 &= B_x (\underbrace{\partial_x A_x + \partial_y A_y + \partial_z A_z}_{\text{div } \vec{A}}) + (\underbrace{A_x \partial_x + A_y \partial_y + A_z \partial_z}_{\vec{A} \cdot \nabla}) B_x
 \end{aligned}
 \left. \vphantom{\begin{aligned} \partial_x (A_x B_x) + \partial_y (A_y B_x) + \partial_z (A_z B_x) \end{aligned}} \right\} \vec{e}_x$$

• slinno 1. za 2. i 3. komponentu

$$\boxed{(\nabla \cdot \vec{A}) \vec{B} + (\vec{A} \cdot \nabla) \vec{B} = \nabla \cdot (\vec{A} \otimes \vec{B})}$$

2. način: ∇ - operator

1) osobina sk. pr. $\vec{a} \cdot \vec{b} = \vec{b} \cdot \vec{a}$

$$\begin{aligned} \nabla \cdot (\vec{A} \otimes \vec{B}) &= \nabla \cdot (\vec{A} \otimes \vec{B}) + \nabla \cdot (\vec{A} \otimes \vec{B}) = \\ &= (\nabla \cdot \vec{A}) \vec{B} + (\vec{A} \cdot \nabla) \vec{B} \end{aligned}$$

② $\nabla \times (\vec{A} \times \vec{B}) = ?$ (uvijek za domaći možete raspisati)

$$\nabla \times (\vec{A} \times \vec{B}) = \nabla \times (\vec{A} \times \vec{B}) + \nabla \times (\vec{A} \times \vec{B})$$

$$\rightarrow \vec{a} \times (\vec{b} \times \vec{c}) = \vec{b} (\vec{a} \cdot \vec{c}) - \vec{c} (\vec{a} \cdot \vec{b})$$

$$\nabla \times (\vec{A} \times \vec{B}) = \vec{A} (\nabla \cdot \vec{B}) - \vec{B} (\nabla \cdot \vec{A}) = (\vec{B} \cdot \nabla) \vec{A} - \vec{B} (\nabla \cdot \vec{A})$$

$$\nabla \times (\vec{A} \times \vec{B}) = -\nabla \times (\vec{B} \times \vec{A}) = - \left[\vec{B} (\nabla \cdot \vec{A}) - \vec{A} (\nabla \cdot \vec{B}) \right] \quad \text{①}$$

$$\rightarrow \vec{a} \times \vec{b} = -\vec{b} \times \vec{a}$$

$$\text{②} \quad \vec{A} (\nabla \cdot \vec{B}) - (\vec{A} \cdot \nabla) \vec{B}$$

$$\nabla \times (\vec{A} \times \vec{B}) = (\vec{B} \cdot \nabla) \vec{A} - \vec{B} (\nabla \cdot \vec{A}) + \vec{A} (\nabla \cdot \vec{B}) - (\vec{A} \cdot \nabla) \vec{B}$$

$$(3) \quad \nabla \cdot (\vec{A} \times \vec{B}) = ?$$

$$\nabla \cdot (\vec{A} \times \vec{B}) = \nabla \cdot \left(\overset{\downarrow}{\vec{A}} \times \overset{\downarrow}{\vec{B}} \right) + \nabla \cdot \left(\vec{A} \times \overset{\downarrow}{\vec{B}} \right) \quad \text{⊖}$$

→ osobina mešovitoq prvizoda:
invarijantna u odnosu na cirkulne permutacije:

$$\vec{a} \cdot (\vec{b} \times \vec{c}) = \vec{c} \cdot (\vec{a} \times \vec{b}) = \vec{b} \cdot (\vec{c} \times \vec{a})$$

$$\text{⊖} \quad \vec{B} \cdot (\nabla \times \vec{A}) - \vec{A} \cdot (\nabla \times \vec{B})$$

$$(4) \quad \nabla \times (\tau \vec{A}) = ?$$

$$\begin{aligned} \nabla \times (\tau \vec{A}) &= \nabla \times \left(\overset{\downarrow}{\tau} \vec{A} \right) + \nabla \times \left(\tau \overset{\downarrow}{\vec{A}} \right) = \\ &= \nabla \tau \times \vec{A} + \tau (\nabla \times \vec{A}) \end{aligned}$$

$$\textcircled{5} \quad \nabla (\vec{A} \cdot \vec{B}) = ?$$

$$\nabla (\vec{A} \cdot \vec{B}) = \underbrace{\nabla (\vec{A} \cdot \vec{B})}_{\downarrow} + \underbrace{\nabla (\vec{A} \cdot \vec{B})}_{\downarrow} \textcircled{=} \textcircled{\neq}$$

$$\begin{aligned} \vec{A} \times (\nabla \times \vec{B}) &= \nabla (\vec{A} \cdot \vec{B}) - \vec{B} (\vec{A} \cdot \nabla) = \\ &= \underbrace{\nabla (\vec{A} \cdot \vec{B})}_{\downarrow} - (\vec{A} \cdot \nabla) \vec{B} \end{aligned}$$

$$\begin{aligned} \vec{B} \times (\nabla \times \vec{A}) &= \nabla (\vec{B} \cdot \vec{A}) - \vec{A} (\vec{B} \cdot \nabla) = \\ &= \underbrace{\nabla (\vec{A} \cdot \vec{B})}_{\downarrow} - (\vec{B} \cdot \nabla) \vec{A} \end{aligned}$$

$$\nabla (\vec{A} \cdot \vec{B}) = \vec{A} \times (\nabla \times \vec{B}) + (\vec{A} \cdot \nabla) \vec{B}$$

$$\nabla (\vec{A} \cdot \vec{B}) = \vec{B} \times (\nabla \times \vec{A}) + (\vec{B} \cdot \nabla) \vec{A}$$

$$\textcircled{=}^* \left\{ \vec{A} \times (\nabla \times \vec{B}) + (\vec{A} \cdot \nabla) \vec{B} + \vec{B} \times (\nabla \times \vec{A}) + (\vec{B} \cdot \nabla) \vec{A} \right\}$$

$$\textcircled{6} \quad \vec{A} \underbrace{(\vec{B} \cdot \vec{C})}_{\text{I}} = \underbrace{(\vec{A} \otimes \vec{B})}_{\text{II}} \cdot \vec{C} \quad (\text{pohazati})$$

(i = 1, 2, 3)

$$\textcircled{I} \quad \vec{A} \cdot (\vec{B} \cdot \vec{C}) = \begin{bmatrix} A_x \\ A_y \\ A_z \end{bmatrix} \cdot \left(\begin{bmatrix} \sum_i B_i C_i \end{bmatrix} \right) = \begin{bmatrix} A_x \sum_i B_i C_i \\ A_y \sum_i B_i C_i \\ A_z \sum_i B_i C_i \end{bmatrix}$$

$$\textcircled{II} \quad (\vec{A} \otimes \vec{B}) \cdot \vec{C} = \left(\begin{bmatrix} A_x \\ A_y \\ A_z \end{bmatrix} [B_x \ B_y \ B_z] \right) \begin{bmatrix} C_1 \\ C_2 \\ C_3 \end{bmatrix} =$$

$$= \begin{bmatrix} A_x B_x & A_x B_y & A_x B_z \\ A_y B_x & A_y B_y & A_y B_z \\ A_z B_x & A_z B_y & A_z B_z \end{bmatrix} \begin{bmatrix} C_x \\ C_y \\ C_z \end{bmatrix} =$$

$$= \begin{bmatrix} A_x B_x C_x + A_x B_y C_y + A_x B_z C_z \\ A_y B_x C_x + A_y B_y C_y + A_y B_z C_z \\ A_z B_x C_x + A_z B_y C_y + A_z B_z C_z \end{bmatrix} = \begin{bmatrix} A_x & \sum_i B_i C_i \\ A_y & \sum_i B_i C_i \\ A_z & \sum_i B_i C_i \end{bmatrix}$$



⑦ Neka je \vec{B} linearna f-ja vektora \vec{A} data

kao:

$$\vec{B} = \vec{a} \times (\hat{B} \times \vec{A}),$$

gde su \vec{a} i \vec{b} poznati vektori.

Određeti tenzor \hat{T} takav da je:

$$\vec{B} = \hat{T} \cdot \vec{A}$$

$$\vec{B} = \vec{a} \times (\vec{b} \times \vec{A}) = \vec{b} (\vec{a} \cdot \vec{A}) - \vec{A} (\vec{a} \cdot \vec{b}) =$$

$$= (\vec{b} \otimes \vec{a}) \cdot \vec{A} - (\vec{a} \cdot \vec{b}) \hat{A} =$$

$$= \left[(\vec{b} \otimes \vec{a}) \cdot \quad - (\vec{a} \cdot \vec{b}) \right] \vec{A} =$$

$$\downarrow$$

$$\cdot \hat{I} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \left[\vec{b} \otimes \vec{a} - (\vec{a} \cdot \vec{b}) \hat{I} \right] \cdot \vec{A}$$

\hat{I}

$$\hat{T} = \begin{bmatrix} -a_2 b_2 - a_3 b_3 & b_1 a_2 & b_1 a_3 \\ b_2 a_1 & -a_1 b_1 - a_3 b_3 & b_2 a_3 \\ b_3 a_1 & b_3 a_2 & -a_1 b_1 - a_2 b_2 \end{bmatrix}$$

(8) Pokazati da je:

$$\text{rot}(\vec{a}(\vec{b} \cdot \vec{r})r^n) = (\vec{b} \times \vec{a})r^n + (\vec{r} \times \vec{a})(\vec{b} \cdot \vec{r})nr^{n-2}, \text{ gde je}$$

\vec{r} -vektor položaja, $r = |\vec{r}|$, \vec{a}, \vec{b} su konst. vektori

$$\begin{aligned} \nabla \times (\uparrow \vec{A}) &= \nabla \times (\uparrow \vec{T} \vec{A}) + \nabla \times (\uparrow \vec{T} \vec{A}) = \\ &= \nabla \uparrow \vec{T} \times \vec{A} + \uparrow \vec{T} (\nabla \times \vec{A}) = \\ &= -\vec{A} \times \nabla \uparrow \vec{T} + \uparrow \vec{T} (\nabla \times \vec{A}) \end{aligned}$$

$$\text{rot}(\vec{a} (\vec{b} \cdot \vec{r}) r^n) = \underbrace{-\vec{a} \times \nabla (\vec{b} \cdot \vec{r}) r^n}_{\text{rot}(\text{const}) = \vec{0}} + (\vec{b} \cdot \vec{r}) r^n \underbrace{(\nabla \times \vec{a})}_{\text{rot}(\text{const}) = \vec{0}}$$

$$\nabla(TP) = P \nabla T + T \nabla P$$

$$\nabla(\vec{b} \cdot \vec{r}) r^n = (\vec{b} \cdot \vec{r}) \nabla r^n + r^n \nabla(\vec{b} \cdot \vec{r})$$

$$|\vec{r}| = r = \sqrt{x^2 + y^2 + z^2}$$

$$\nabla(r^n) = \nabla\left((x^2 + y^2 + z^2)^{\frac{n}{2}}\right) = \begin{bmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{bmatrix} \left[(x^2 + y^2 + z^2)^{n/2} \right]$$

$$= n r^{n-2} \vec{r}$$

by $\frac{\partial}{\partial x}$ $\frac{\partial}{\partial y}$ $\frac{\partial}{\partial z}$

$$\nabla (\vec{b} \cdot \vec{r}) = \nabla (b_x x + b_y y + b_z z) = \vec{b}$$

$$\begin{aligned} \text{rot} (\vec{a} (\vec{b} \cdot \vec{r}) r^n) &= -\vec{a} \times \left[(\vec{b} \cdot \vec{r}) n r^{n-2} \vec{r} + r^n \vec{b} \right] = \\ &= (\vec{r} \times \vec{a}) (\vec{b} \cdot \vec{r}) n r^{n-2} + (\vec{b} \times \vec{a}) r^n \quad \square \end{aligned}$$